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And Control Engineering) By Hyo-Sung Ahn**

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**Robust stability of iterative learning control**

2.2 Dynamics over the trials The iterative learning problem consists of applying the control repeatedly  
over a number of trials, each of length  $T$ , with the aim of

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This paper presents a stability analysis of the iterative learning control interval uncertainty Hyo-Sung  
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The simpler the recursive form  $F(\cdot, \cdot)$ , the better it is for practical implementation of the iterative learning control law, as long as the convergence is assured

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