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Convergence For Interval Systems (Communications
And Control Engineering) By Hyo-Sung Ahn**

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Iterative learning control an optimization

The area of iterative learning control (ILC) has emerged from robotics to form a new and exciting challenge for control theorists and practitioners. There is gr

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Robust stability of iterative learning control

2.2 Dynamics over the trials The iterative learning problem consists of applying the control repeatedly over a number of trials, each of length T , with the aim of

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Monotonic Convergent Iterative Learning Controller Design Based on Interval Model Conversion

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